

## Extreme Hexapod 2 Robot



### **Model Number [BUG\_EH 2-KT] Extreme Hexapod 2 Robot Kit**

- Two degrees of freedom (DOF) per leg
- Robot chassis and servos only, no electronics
- All of the leg joints centering is mechanically adjustable
- Servo motion control = local closed loop
- Motion speed = More than 12" per second
- Height = 5.5"
- Width = 17" (leg to leg)
- Length = 13.5"
- Ground clearance = 3.5"
- Weight (without batteries) = 44 oz
- Servo voltage = 6 vdc (Std servos used at 7.2vdc)

**Model Number [BUG\_EH 2-NS]  
Extreme Hexapod 2**

- Two degrees of freedom (DOF) per leg
- Robot chassis only, no electronics, no servos
- All of the leg joints centering is mechanically adjustable
- Servo motion control = local closed loop
- Motion speed = More than 12" per second
- Height = 5.5"
- Width = 17" (leg to leg)
- Length = 13.5"
- Ground clearance = 3.5"
- Weight (without batteries) = 44 oz
- Servo voltage = 6 vdc (Std servos used at 7.2vdc)