

## Extreme Hexapod 3 Robot



### **Model Number [BUG\_EH 3-KT] Extreme Hexapod 3 Robot Kit**

- The three DOF (degree of freedom) leg design means this robot can walk side to side (crab walk)
- Robot chassis and servos only, no electronics
- Servo motion control = local closed loop
- Steering = differential
- Number of legs = 6
- Degrees of freedom per leg = 3
- Motion speed = TBA
- Height (body) = 2.0"
- Height (overall) = up to 7.0"
- Width (body) = 3.75"
- Width (overall) = 17.0"
- Length (body) = 14.25"

- Length (overall) = 16.0"
- Weight (w/out batteries) = 3lb 10oz
- Ground clearance = up to 5.0"

**Model Number [BUG\_EH 3-NS]**  
**Extreme Hexapod 3**

- The three DOF (degree of freedom) leg design means this robot can walk side to side (crab walk)
- Robot chassis only, no electronics, no servos
- Servo motion control = local closed loop
- Steering = differential
- Number of legs = 6
- Degrees of freedom per leg = 3
- Motion speed = TBA
- Height (body) = 2.0"
- Height (overall) = up to 7.0"
- Width (body) = 3.75"
- Width (overall) = 17.0"
- Length (body) = 14.25"
- Length (overall) = 16.0"
- Weight (w/out batteries) = 3lb 10oz
- Ground clearance = up to 5.0"